
function TREE-SEARCH(*start*, *problem*, ENQUEUE) **returns** a solution, or failure
 frontier ← QUEUE(NODE-INIT(*start*))
 do
 if EMPTY(*frontier*) **then return** failure
 node ← FIRST(*frontier*)
 if GOAL(*problem*, STATE(*node*)) **then return** SOLUTION(*node*)
 frontier ← ENQUEUE(EXPAND(*problem*, *node*), REST(*frontier*))

function EXPAND(*problem*, *node*) **returns** a set of nodes
 successors ← []
 current ← STATE(*node*)
 for each *action* **in** ACTIONS(*problem*, *current*)
 next ← RESULT(*problem*, *current*, *action*)
 if not CONTAINS(PATH(*node*), *next*) **then**
 successors ←
 [CHILD-NODE(*problem*, *node*, *action*) | *successors*]
